DJI Terra Quality Report

V3.1.1 | 2026-03-03 08:04 | Mission: 618625

Quality Report for LiDAR Point Cloud Processing

Aircraft Data Collection Time



POS Data Collection Time	55min 33s
Point Cloud Data Collection Time	55min 22s

Software Processing Time



POS Calculation	17min 52s
Point Cloud Optimization Time	2h 2min 8s
• POS Calculation	17min 52s
• Point Cloud Accuracy Optimization Time	59min 59s
• Smoothing Point Cloud Time	17min 32s
• Point Cloud Colorization Time	5min 47s
• Merging Output Time	2s
• Output Saving Time	14min 48s
• Others	28min 7s
3D Mesh Generation Time	1h 50min 20s

Reconstruction Parameters

Point Cloud Optimization Parameters

POS Calculation	**Data POS**
Scenario	**Point Cloud Processing**
LiDAR Calibration	**Yes**
Point Cloud Density (By Percentage)	**High(100%)**
Computation Method	**Standalone Computation**

Point Cloud Output Parameters

Point Cloud Format	**PNTS**
Merged Output	**Yes**
LiDAR Point Cloud Block Count	**1**
2D Map	**No**
File Format	**RJSM | PLY**
Quality	**High**
Reduce Model to	**100%**
Gaussian Splatting	**No**
Output Coordinate System	**WGS 84 / UTM zone 32N | Default**

Mission Parameters

Flight Parameters (1 Flights)

Hardware Parameters

Payload	**DJI Zenmuse L2**
Payload SN	**61JD56EN00502J**
LiDAR Parameters	**https://enterprise.dji.com/zenmuse-l2/specs**

LiDAR and IMU Calibration Parameters

Parameters	X	Y	Z	roll	pitch	yaw
Before Calibration	**0.02667m**	**0.01456m**	**-0.04615m**	**-3.1305732 rad**	**0.0029999 rad**	**0.0125964 rad**
After Calibration	**0.02667m**	**0.01456m**	**-0.04615m**	**-3.1304826 rad**	**0.0035419 rad**	**0.0128598 rad**

Flight Parameters

Average Flight Speed	**4.44m/s**
Flight Height	**82.57m**
Ground Beam Diameter	**100mm*33mm**
FOV	**70°*3°**
Pulse Rate	**240kHz**
Scan Rate	**120Hz/Hz**
Scan Mode	**Linear**

Flight Parameters (2 Flights)

Hardware Parameters

Payload	**DJI Zenmuse L2**
Payload SN	**61JD56EN00502J**
LiDAR Parameters	**https://enterprise.dji.com/zenmuse-l2/specs**

LiDAR and IMU Calibration Parameters

Parameters	X	Y	Z	roll	pitch	yaw
Before Calibration	**0.02667m**	**0.01456m**	**-0.04615m**	**-3.1305732 rad**	**0.0029999 rad**	**0.0125964 rad**
After Calibration	**0.02667m**	**0.01456m**	**-0.04615m**	**-3.1304826 rad**	**0.0035419 rad**	**0.0128598 rad**

Flight Parameters

Average Flight Speed	**4.14m/s**
Flight Height	**29.69m**
Ground Beam Diameter	**35mm*11mm**
FOV	**70°*3°**
Pulse Rate	**240kHz**
Scan Rate	**120Hz/Hz**
Scan Mode	**Linear**

Flight Parameters (3 Flights)

Hardware Parameters

Payload	**DJI Zenmuse L2**
Payload SN	**61JD56EN00502J**
LiDAR Parameters	**https://enterprise.dji.com/zenmuse-l2/specs**

LiDAR and IMU Calibration Parameters

Parameters	X	Y	Z	roll	pitch	yaw
Before Calibration	**0.02667m**	**0.01456m**	**-0.04615m**	**-3.1305732 rad**	**0.0029999 rad**	**0.0125964 rad**
After Calibration	**0.02667m**	**0.01456m**	**-0.04615m**	**-3.1304826 rad**	**0.0035419 rad**	**0.0128598 rad**

Flight Parameters

Average Flight Speed	**4.26m/s**
Flight Height	**5.43m**
Ground Beam Diameter	**6mm*2mm**
FOV	**70°*3°**
Pulse Rate	**240kHz**
Scan Rate	**120Hz/Hz**
Scan Mode	**Linear**

Flight Parameters (4 Flights)

Hardware Parameters

Payload	**DJI Zenmuse L2**
Payload SN	**61JD56EN00502J**
LiDAR Parameters	**https://enterprise.dji.com/zenmuse-l2/specs**

LiDAR and IMU Calibration Parameters

Parameters	X	Y	Z	roll	pitch	yaw
Before Calibration	**0.02667m**	**0.01456m**	**-0.04615m**	**-3.1305732 rad**	**0.0029999 rad**	**0.0125964 rad**
After Calibration	**0.02667m**	**0.01456m**	**-0.04615m**	**-3.1304826 rad**	**0.0035419 rad**	**0.0128598 rad**

Flight Parameters

Average Flight Speed	**4.82m/s**
Flight Height	**55.02m**
Ground Beam Diameter	**66mm*22mm**
FOV	**70°*3°**
Pulse Rate	**240kHz**
Scan Rate	**120Hz/Hz**
Scan Mode	**Linear**

Flight Parameters (5 Flights)

Hardware Parameters

Payload	**DJI Zenmuse L2**
Payload SN	**61JD56EN00502J**
LiDAR Parameters	**https://enterprise.dji.com/zenmuse-l2/specs**

LiDAR and IMU Calibration Parameters

Parameters	X	Y	Z	roll	pitch	yaw
Before Calibration	**0.02667m**	**0.01456m**	**-0.04615m**	**-3.1305732 rad**	**0.0029999 rad**	**0.0125964 rad**
After Calibration	**0.02667m**	**0.01456m**	**-0.04615m**	**-3.1304826 rad**	**0.0035419 rad**	**0.0128598 rad**

Flight Parameters

Average Flight Speed	**3.91m/s**
Flight Height	**65.69m**
Ground Beam Diameter	**78mm*26mm**
FOV	**70°*3°**
Pulse Rate	**240kHz**
Scan Rate	**120Hz/Hz**
Scan Mode	**Linear**

Flight Parameters (6 Flights)

Hardware Parameters

Payload	**DJI Zenmuse L2**
Payload SN	**61JD56EN00502J**
LiDAR Parameters	**https://enterprise.dji.com/zenmuse-l2/specs**

LiDAR and IMU Calibration Parameters

Parameters	X	Y	Z	roll	pitch	yaw
Before Calibration	**0.02667m**	**0.01456m**	**-0.04615m**	**-3.1305732 rad**	**0.0029999 rad**	**0.0125964 rad**
After Calibration	**0.02667m**	**0.01456m**	**-0.04615m**	**-3.1304826 rad**	**0.0035419 rad**	**0.0128598 rad**

Flight Parameters

Average Flight Speed	**4.21m/s**
Flight Height	**64.83m**
Ground Beam Diameter	**77mm*25mm**
FOV	**70°*3°**
Pulse Rate	**240kHz**
Scan Rate	**120Hz/Hz**
Scan Mode	**Linear**

Flight Parameters (7 Flights)

Hardware Parameters

Payload	**DJI Zenmuse L2**
Payload SN	**61JD56EN00502J**
LiDAR Parameters	**https://enterprise.dji.com/zenmuse-l2/specs**

LiDAR and IMU Calibration Parameters

Parameters	X	Y	Z	roll	pitch	yaw
Before Calibration	**0.02667m**	**0.01456m**	**-0.04615m**	**-3.1305732 rad**	**0.0029999 rad**	**0.0125964 rad**
After Calibration	**0.02667m**	**0.01456m**	**-0.04615m**	**-3.1304826 rad**	**0.0035419 rad**	**0.0128598 rad**

Flight Parameters

Average Flight Speed	**4.82m/s**
Flight Height	**108.31m**
Ground Beam Diameter	**225mm*75mm**
FOV	**70°*3°**
Pulse Rate	**240kHz**
Scan Rate	**120Hz/Hz**
Scan Mode	**Linear**

System Parameters

CPU	**Intel Xeon 24 cores**
GPU Count	**1**
GPU ①	**NVIDIA GeForce RTX 4090**
RAM	**512780 M**

Accuracy Parameters

POS Status

Fix	**100.00%**
Other	**0.00%**

IMU Trajectory Error

Parameters	X(E) RMSE	Average X(E)	Y(N) RMSE	Average Y(N)	Z(U) RMSE	Average Z(U)
Location	**0.00009 m**	**0.00574 m**	**0.00008 m**	**0.00515 m**	**0.0001 m**	**0.00664 m**
Attitude	**0.00000443 rad**	**0.00006147 rad**	**0.00000821 rad**	**0.00006577 rad**	**0.00000371 rad**	**0.00012341 rad**

Flight Strip Accuracy

Number of Flight Strips	Average Altitude Difference	Average Overlap Rate	Altitude Tolerance	Speed Consistency	Flight Route Curvature
7	**74.27624 m**	**23.097%**	**131.4185 m**	**0.21%**	**0.63°**

Flight strip accuracy file is in the report/flight_strip_accuracy folder under the project folder

Point Cloud Accuracy

Point Cloud Density

Scale	Point Cloud Average Density	Point Cloud Standard Density	Grid Side Length	Total Grid Number	Non-conforming Grid Ratio
1:500	**194ppoints/m²**	**16points/m²**	**0.25 m**	**6549624**	**1.08%**
1:1000	**194ppoints/m²**	**4points/m²**	**0.5 m**	**1643188**	**0.47%**
1:2000	**194ppoints/m²**	**1points/m²**	**1 m**	**412628**	**0.56%**

Output Parameters

Output List

Point Cloud PNTS LAZ

Model: BODM PLY